

Self-Supervised Learning in Computer Vision: Past, Present, Trends

Han Hu (胡瀚)

Visual Computing Group

Microsoft Research Asia (MSRA)

October 10th, 2021 @ VALSE

Yann LeCun's Cake Analogy

- ▶ **“Pure” Reinforcement Learning (cherry)**

- ▶ The machine predicts a scalar reward given once in a while.

- ▶ **A few bits for some samples**

- ▶ **Supervised Learning (icing)**

- ▶ The machine predicts a category or a few numbers for each input

- ▶ Predicting human-supplied data

- ▶ **10→10,000 bits per sample**

- ▶ **Self-Supervised Learning (cake génoise)**

- ▶ The machine predicts any part of its input for any observed part.

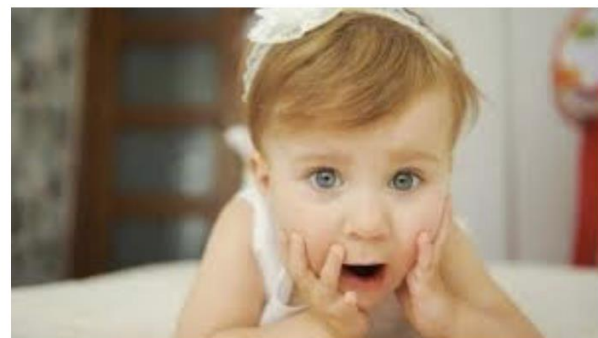
- ▶ Predicts future frames in videos

- ▶ **Millions of bits per sample**



Why Self-Supervised Learning?

- Baby learns to see the world largely by observation



**Photos courtesy of
Emmanuel Dupoux**

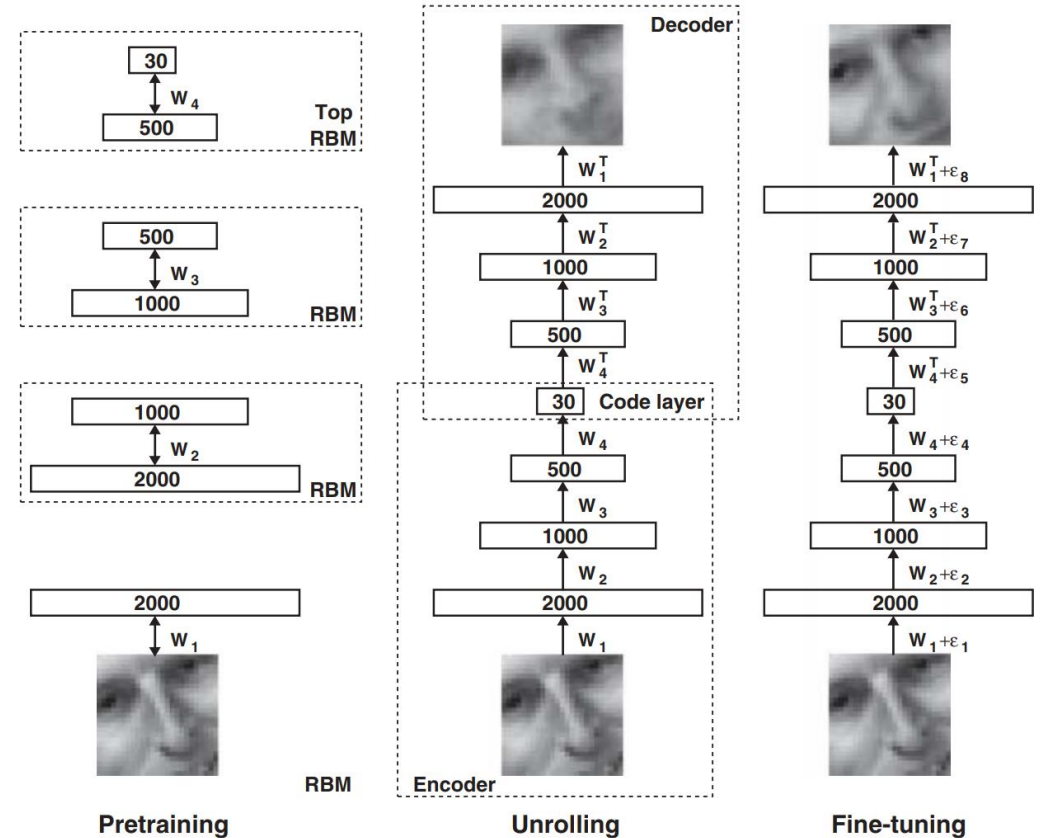
Credit by Yann LeCun

SSL Opened Deep Learning

Science, 2006

Reducing the Dimensionality of Data with Neural Networks

G. E. Hinton* and R. R. Salakhutdinov

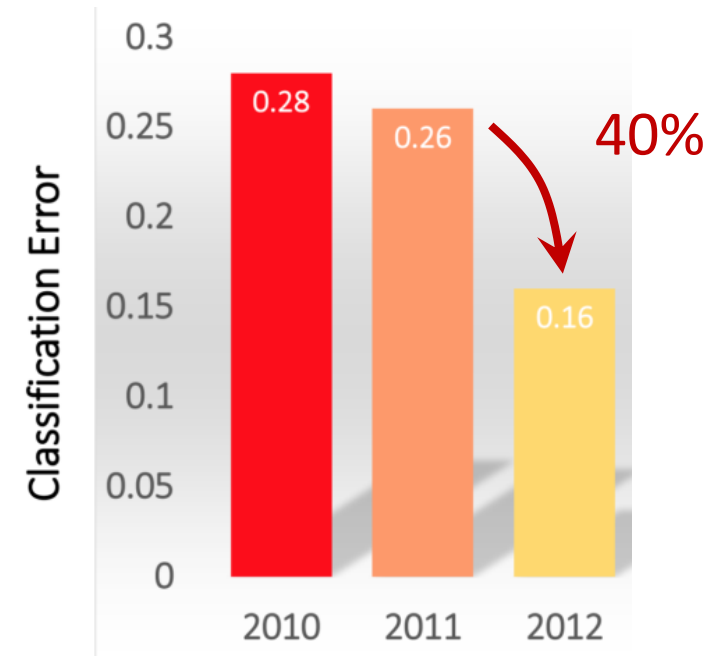


Burst of Deep Learning in Computer Vision

- Supervised learning using AlexNet (NeurIPS'2012)



ImageNet Challenge

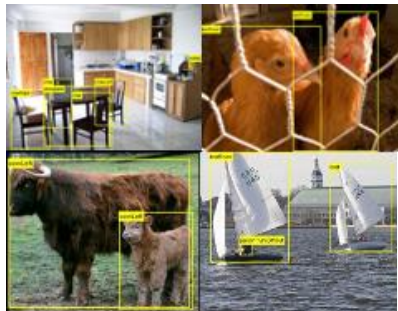


Supervised Pre-training + Fine-tuning

Pretraining on ImageNet Classification



↓ Finetuning



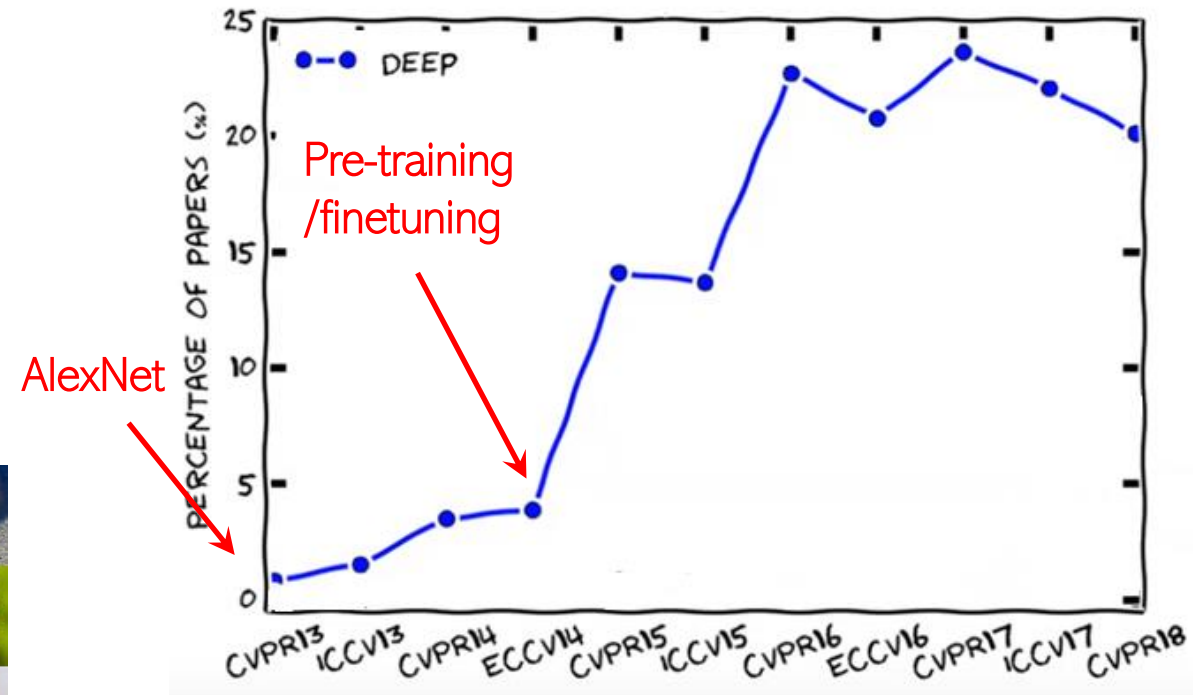
Object Detection



Semantic Segmentation



Fine-grained Classification



Renaissance of Self-Supervised Learning

- **Self-Supervised** Pretraining + Finetuning

Momentum Contrast for Unsupervised Visual Representation Learning

Kaiming He Haoqi Fan Yuxin Wu Saining Xie Ross Girshick

Facebook AI Research (FAIR)

Code: <https://github.com/facebookresearch/moco>

2019.11

MoCo

FAIR

- For the first time, unsupervised pretraining outperform supervised pretraining on 7 down-stream tasks

Renaissance of Self-Supervised Learning

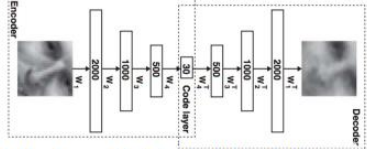
- Similar way as that of human baby learning
- Can utilize unlimited data ???



How Did We Get Here?

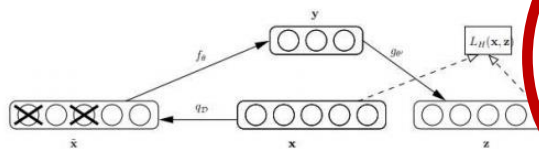
Credit mostly by Andrew Zisserman

Autoencoders




Hinton & Salakhutdinov.
Science 2006.

Denoising Autoencoders



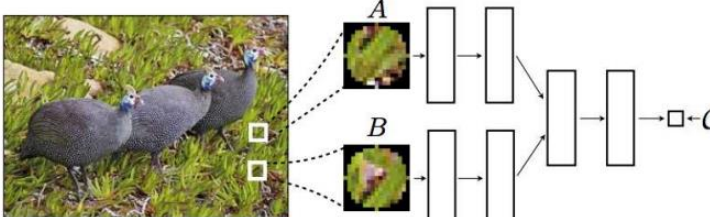
Vincent *et al.* ICML 2008.

Exemplar networks




Dosovitskiy *et al.*, NIPS 2014

Co-Occurrence



Isola *et al.* ICLR Workshop 2016.

Egomotion



Agrawal *et al.* ICCV 2015 Jayaraman *et al.* ICCV 2015

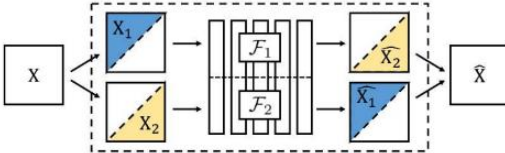
Context



Noroozi *et al.* 2016

Pathak *et al.* CVPR 2016

Split-brain auto-encoders



Zhang *et al.* CVPR 2017

How Did We Get Here?

2014.6

Exemplar

**Dosovitskiy et al,
NIPS'2014**

2018.5

Memory bank

Wu et al, CVPR'2018

2018.12

**Deep metric
transfer**

MSRA

2019.11

MoCo

FAIR

Image #1

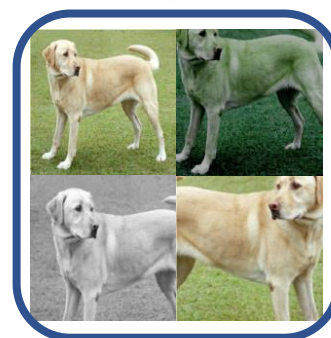


Image #2



Image #3



Pre-text task: Image discrimination

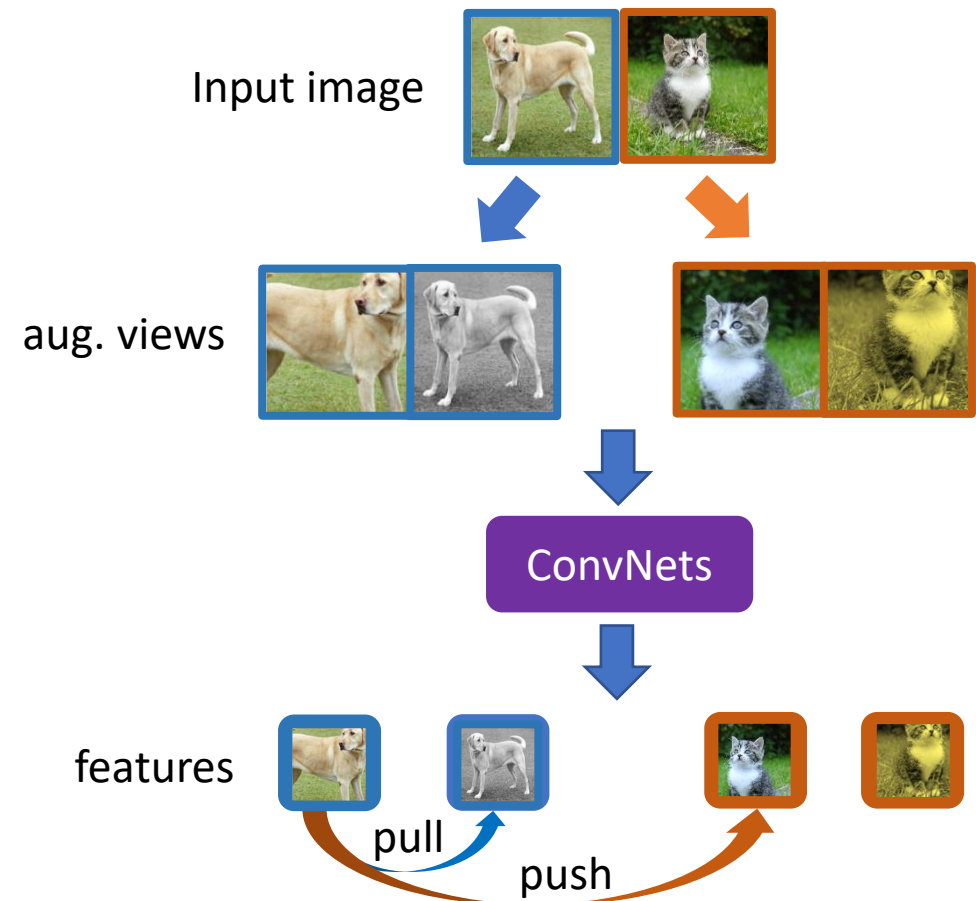
- For the first time, unsupervised pretraining outperform supervised pretraining on 7 down-stream tasks

Contrastive Learning for Instance Discrimination

contrastive learning

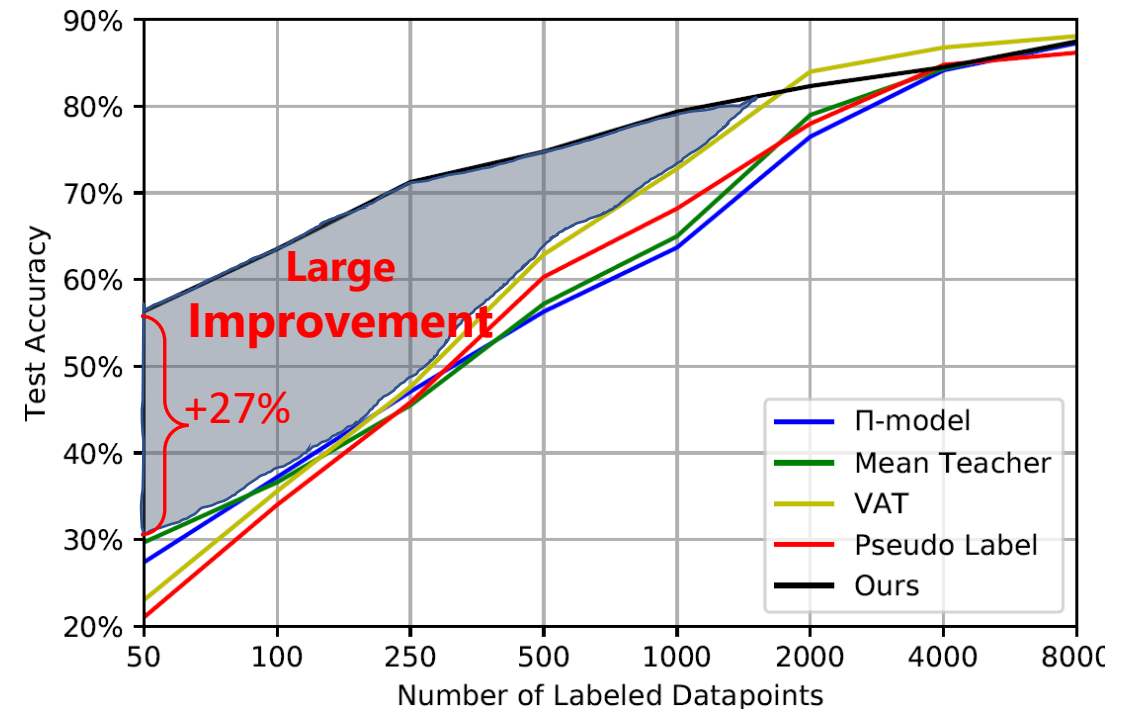


Pre-text task: Image discrimination



Self-supervised pre-training for semi-supervised learning (2018)

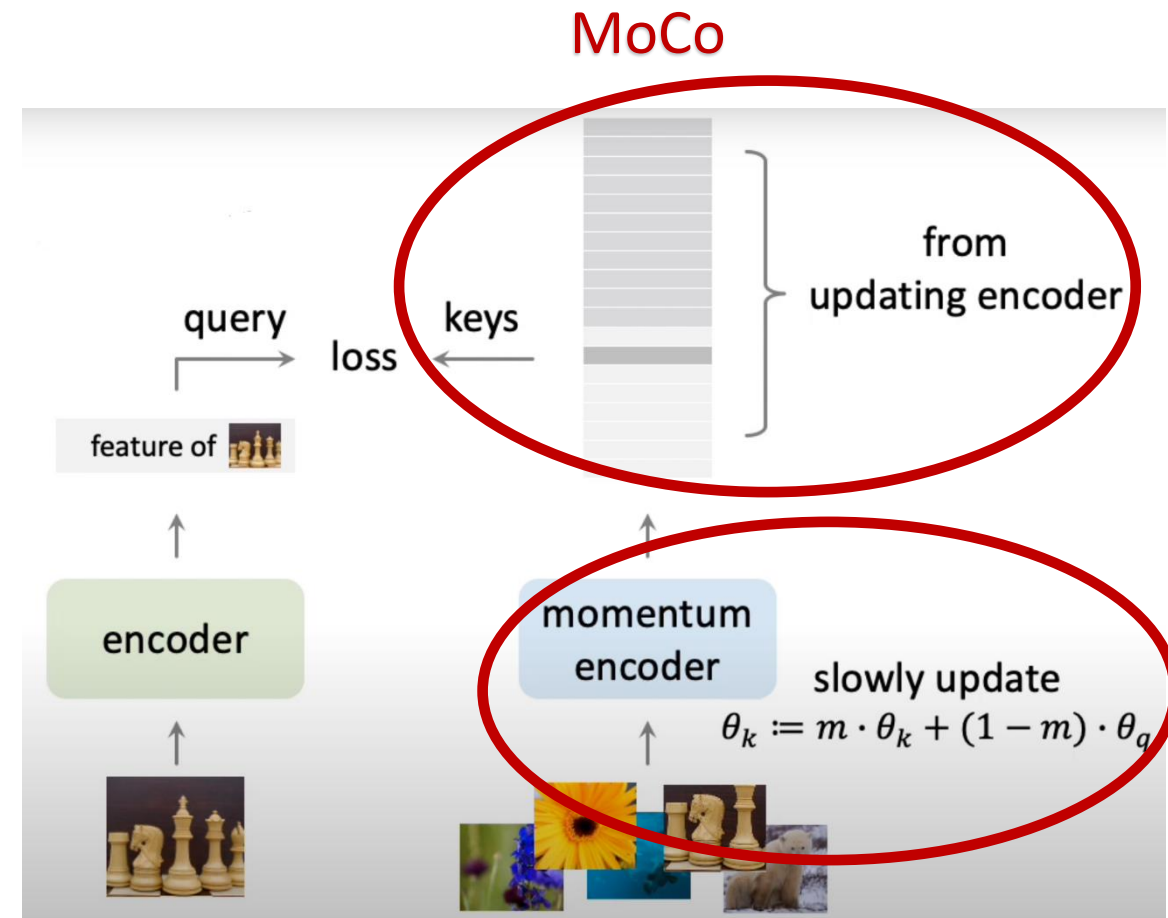
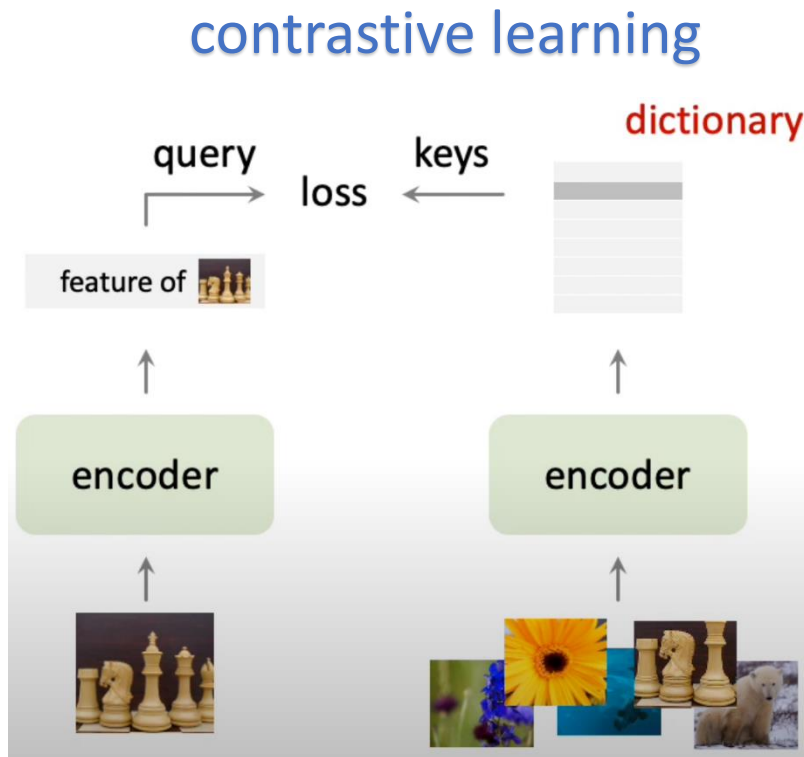
- Demonstrating value of self-supervised pre-training on concrete problems
- Liu et al. Deep Metric Transfer for Label Propagation with Limited Annotated Data, Tech report 2018



MoCo (CVPR'2020)

Credit by Kaiming He

- Large dictionary
- Consistent dictionary by momentum encoder

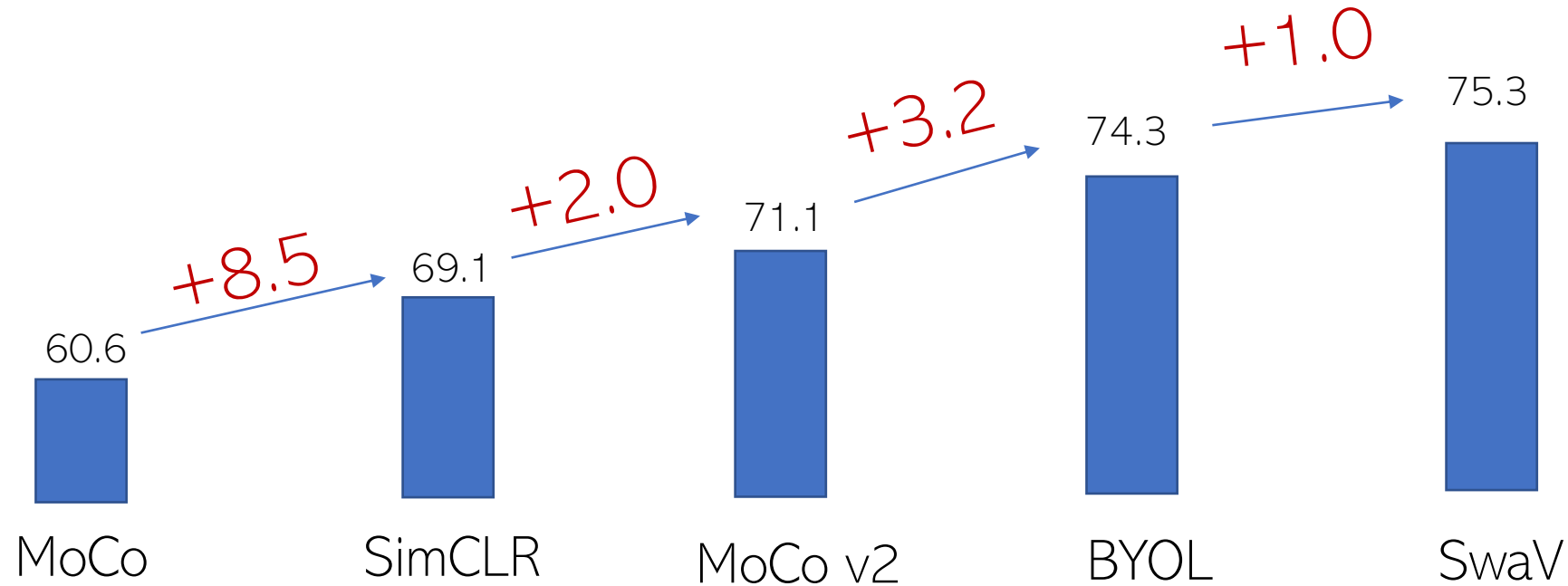


Renaissance of SSL

2019.11-2020.10

Main Theme

- Improving ImageNet-1 K linear evaluation (top-1 acc)



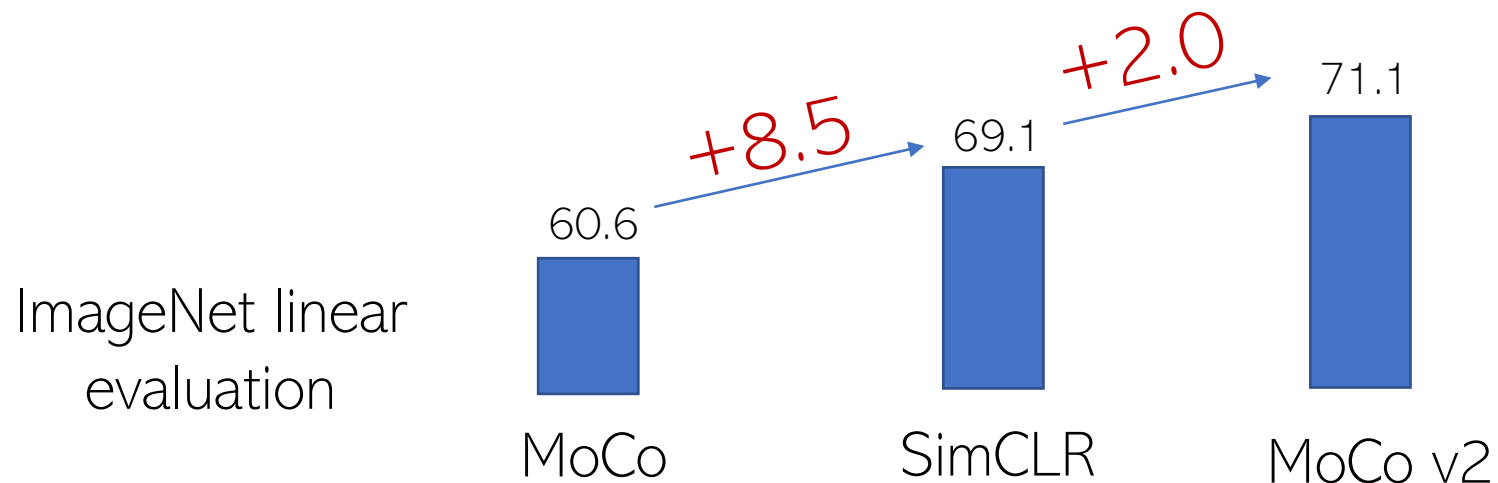
Totally absolute 14.7% improvements in 6 months!

Representative Works

- SimCLR (ICML'2020)
- SimCLR v2 (NeurIPS'2020)
- BYOL (NeurIPS'2020)
- SwaV (NeurIPS'2020)
- PIC (NeurIPS'2020)
- ...

SimCLR (ICML'2020)

- **Simpler**: no momentum, no memory (dictionary)
- **Sufficient distance** between pretext tasks and downstream tasks
 - a linear projection layer -> a MLP layer
- Self-supervised learning benefit significantly from **longer training**



More Insights in SimCLR

- Self-supervised learning benefit more from **larger models**
- Self-supervised learning benefit significantly for **semi-supervised learning**

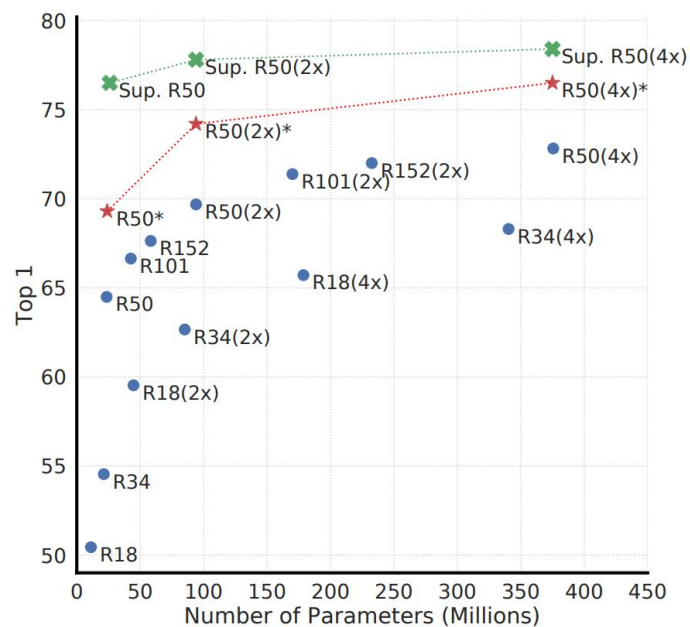


Figure 7. Linear evaluation of models with varied depth and width. Models in blue dots are ours trained for 100 epochs, models in red stars are ours trained for 1000 epochs, and models in green crosses are supervised ResNets trained for 90 epochs⁷ (He et al., 2016).

Method	Architecture	Label fraction	
		1%	10%
Top 5			
Supervised baseline	ResNet-50	48.4	80.4
<i>Methods using other label-propagation:</i>			
Pseudo-label	ResNet-50	51.6	82.4
VAT+Entropy Min.	ResNet-50	47.0	83.4
UDA (w. RandAug)	ResNet-50	-	88.5
FixMatch (w. RandAug)	ResNet-50	-	89.1
S4L (Rot+VAT+En. M.)	ResNet-50 (4x)	-	91.2
<i>Methods using representation learning only:</i>			
InstDisc	ResNet-50	39.2	77.4
BigBiGAN	RevNet-50 (4x)	55.2	78.8
PIRL	ResNet-50	57.2	83.8
CPC v2	ResNet-161(*)	77.9	91.2
SimCLR (ours)	ResNet-50	75.5	87.8
SimCLR (ours)	ResNet-50 (2x)	83.0	91.2
SimCLR (ours)	ResNet-50 (4x)	85.8	92.6

+27.1

Table 7. ImageNet accuracy of models trained with few labels.

SimCLR v2 (NeurIPS'2020)

- “Big Self-Supervised Models are Strong Semi-Supervised Learners”

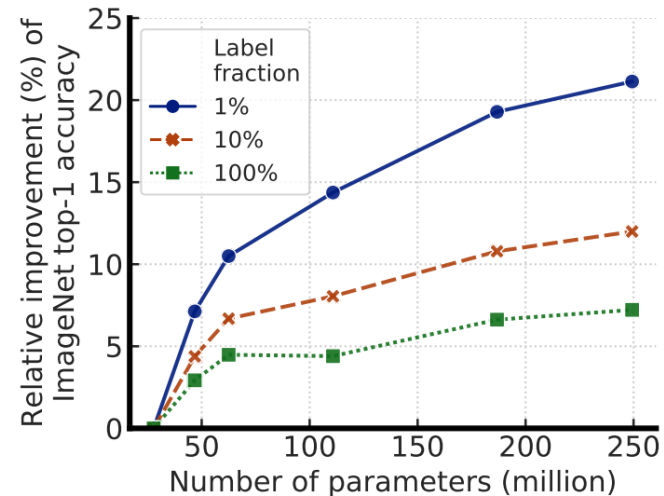
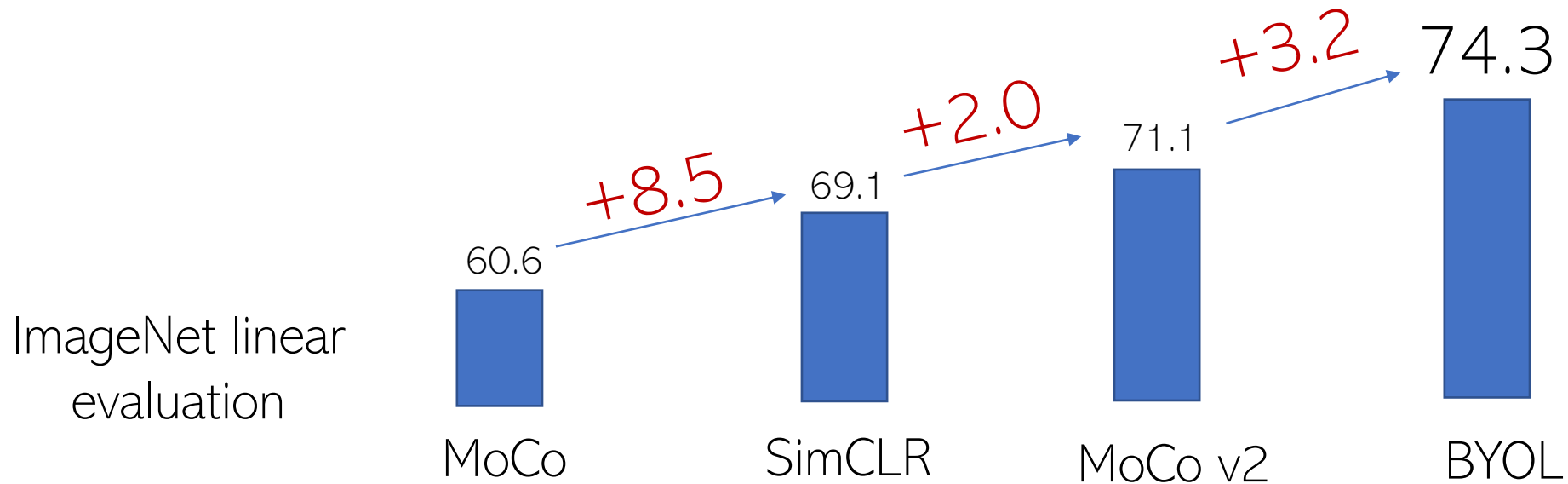


Figure 1: Bigger models yield larger gains when fine-tuning with fewer labeled examples.

Similar as that of GPT-3 in NLP!

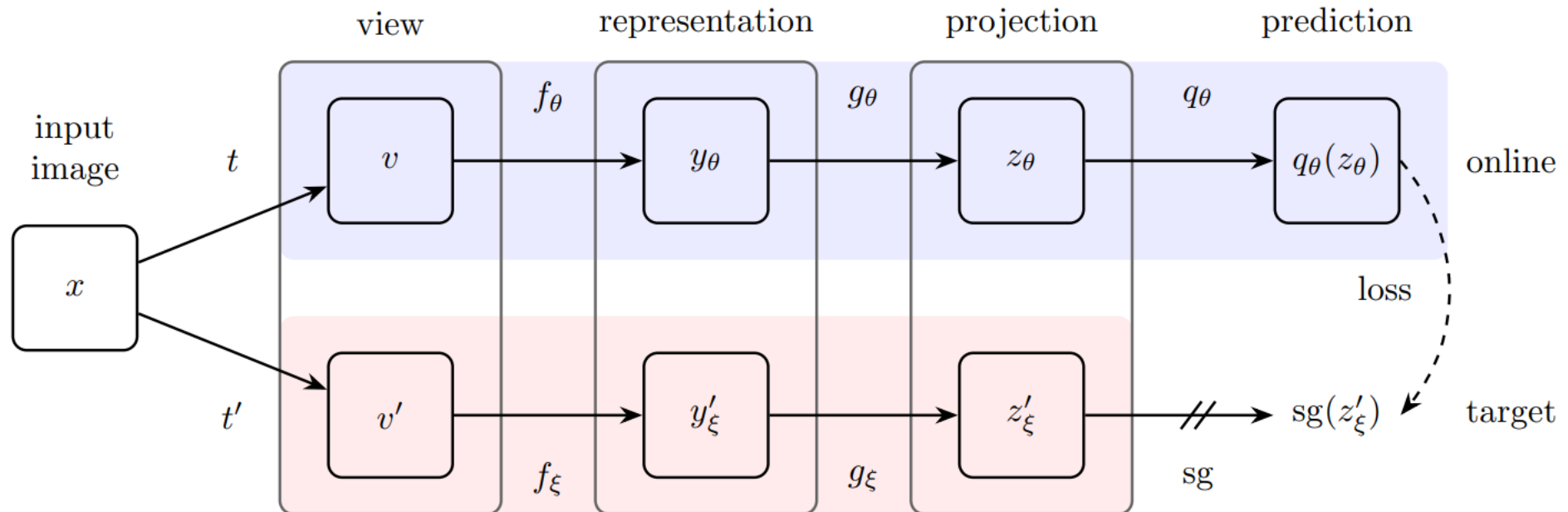
BYOL (NeurIPS'2020)

- Bootstrap Your Own Latent



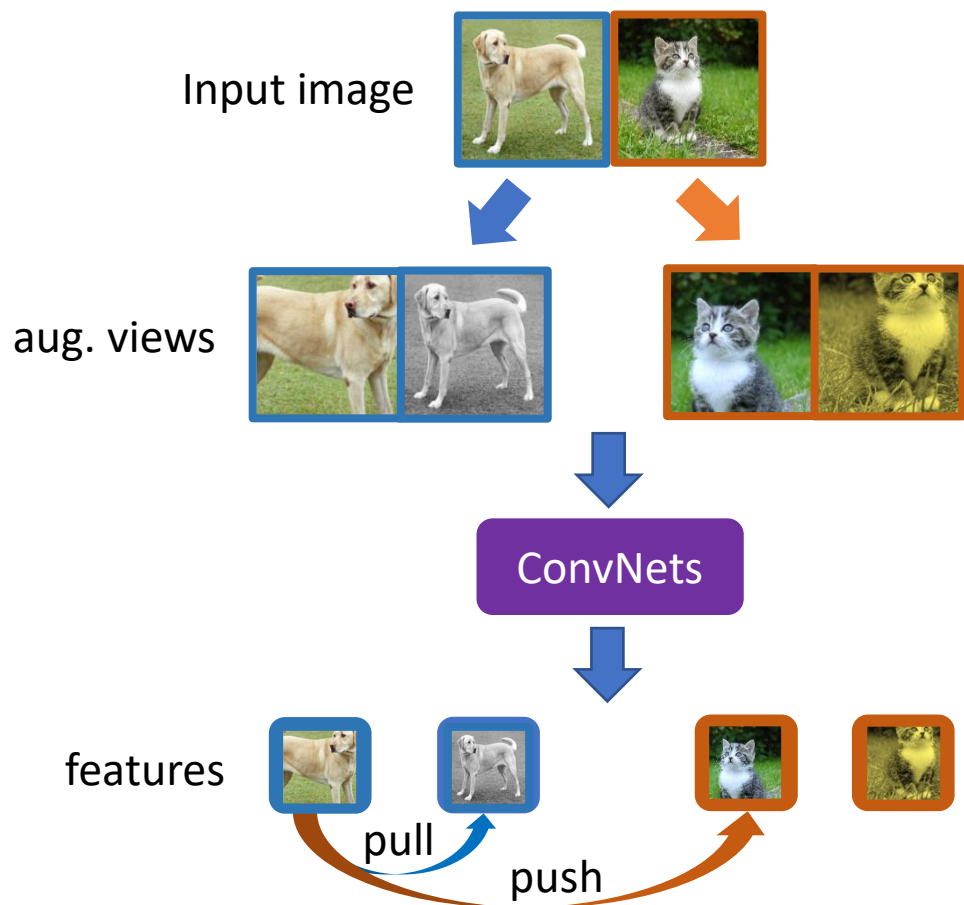
A Finding by BYOL

- MoCo: we need larger dictionary size (more negative pairs)
- BYOL: we do not need negative pairs anymore
 - an asymmetric design

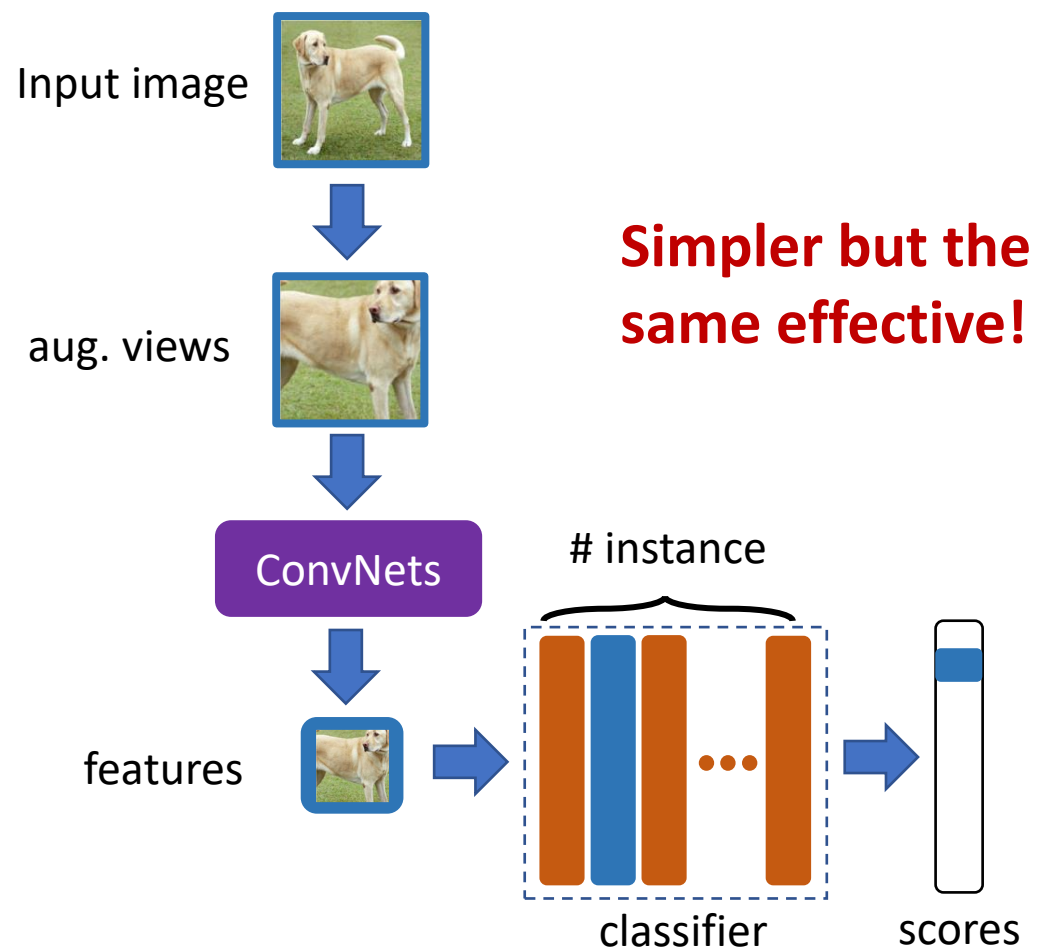


PIC: a Single-Branch Method (NeurIPS'2020)

two-branch methods
(almost all previous methods)



one-branch method (PIC)



The Past Year's Trends

2020.11-present

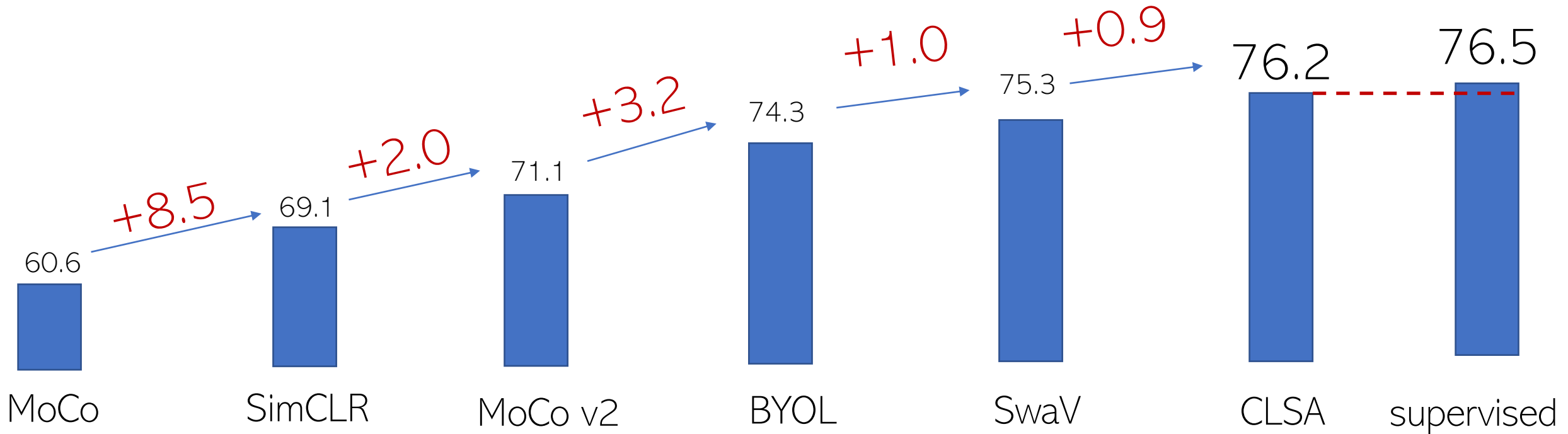
Three Main Trends during the Last Year

- More study on why BYOL does not collapse
 - BYOL (Arxiv v3), SimSiam (CVPR'2021), NonContrastiveSSL (ICML'2021)
- Pre-training good features for **down-stream tasks**
 - Pixel-level pre-training
 - *PixPro*, DenseCL (CVPR'2021)
 - Object-level pre-training
 - SoCo (NeurIPS'2021)
 - Other than contrastive learning
 - BEiT (Tech Report 2021)

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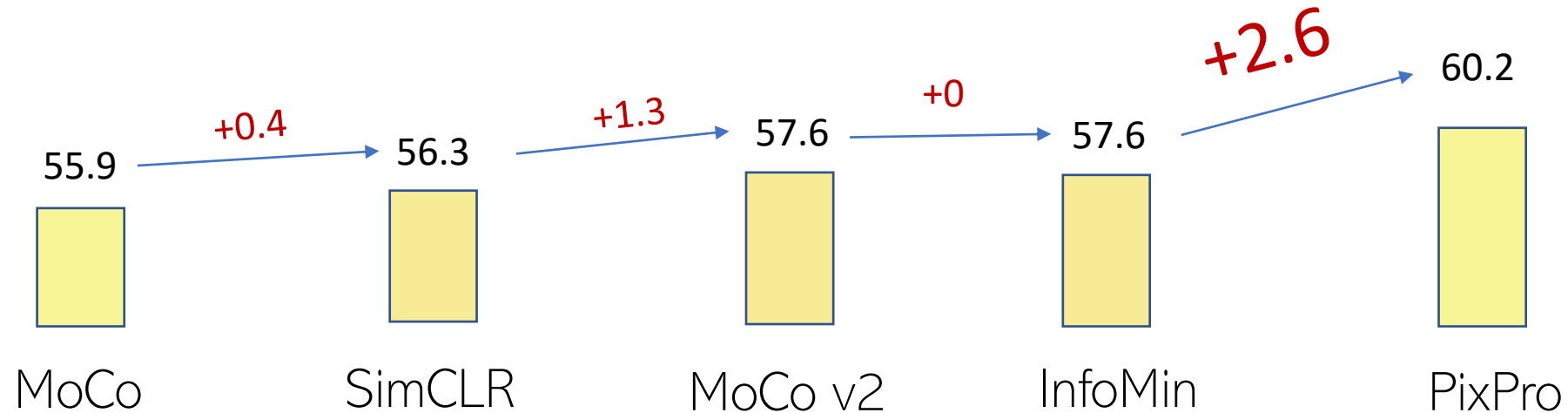
Improvements on ImageNet-1 K linear evaluation



Totally 15.6% absolute improvements in 1 year!

Improvements on Pascal VOC object detection

- PixPro (CVPR'2021)



Totally 1.7% absolute improvements in 1 year!

PixPro Results

- VOC detection (+2.6 mAP)
- COCO FPN detection (+0.8 mAP) COCO C4 (+1.0 mAP)
- Cityscape segmentation (+1.0 mIoU)

Method	#. Epoch	Pascal VOC (R50-C4)			COCO (R50-FPN)			COCO (R50-C4)			Cityscapes (R50) mIoU
		AP	AP ₅₀	AP ₇₅	mAP	AP ₅₀	AP ₇₅	mAP	AP ₅₀	AP ₇₅	
scratch	-	33.8	60.2	33.1	32.8	51.0	35.3	26.4	44.0	27.8	65.3
supervised	100	53.5	81.3	58.8	39.7	59.5	43.3	38.2	58.2	41.2	74.6
MoCo [18]	200	55.9	81.5	62.6	39.4	59.1	43.0	38.5	58.3	41.6	75.3
SimCLR [8]	1000	56.3	81.9	62.5	39.8	59.5	43.6	38.4	58.3	41.6	75.8
MoCo v2 [9]	800	57.6	82.7	64.4	40.4	60.1	44.3	39.5	59.0	42.6	76.2
InfoMin [30]	200	57.6	82.7	64.6	40.6	60.6	44.6	39.0	58.5	42.0	75.6
InfoMin [30]	800	57.5	82.5	64.0	40.4	60.4	44.3	38.8	58.2	41.7	75.6
<i>PixPro</i> (ours)	100	58.8	83.0	66.5	41.3	61.3	45.4	39.6	59.2	42.8	76.8
<i>PixPro</i> (ours)	400	60.2	83.8	67.7	41.4	61.6	45.4	40.5	59.8	44.0	77.2

+2.6 mAP

+0.8 mAP

+1.0 mAP

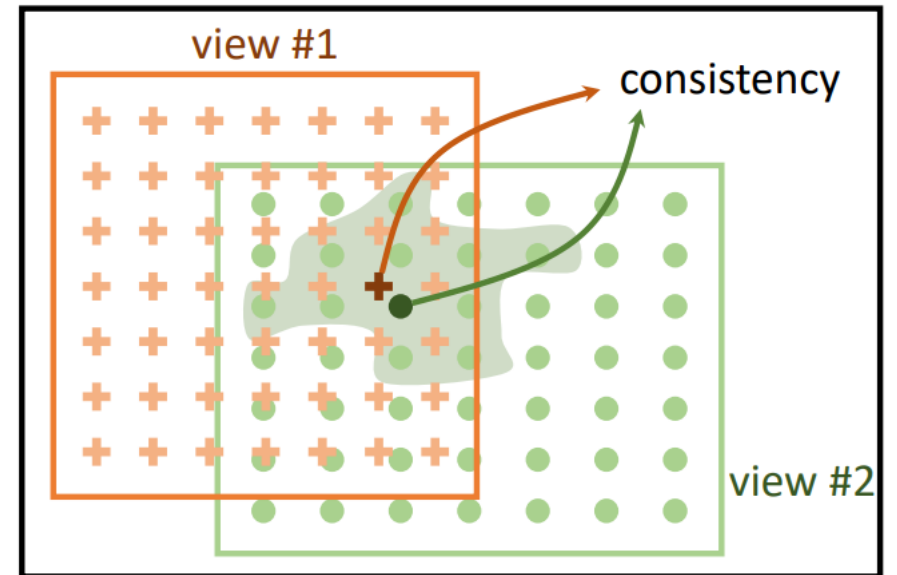
+1.0 mIoU

From Instance-Level to Pixel-Level Learning

Memory bank, MoCo,
SimCLR, BYOL, SwaV, PIC, ...

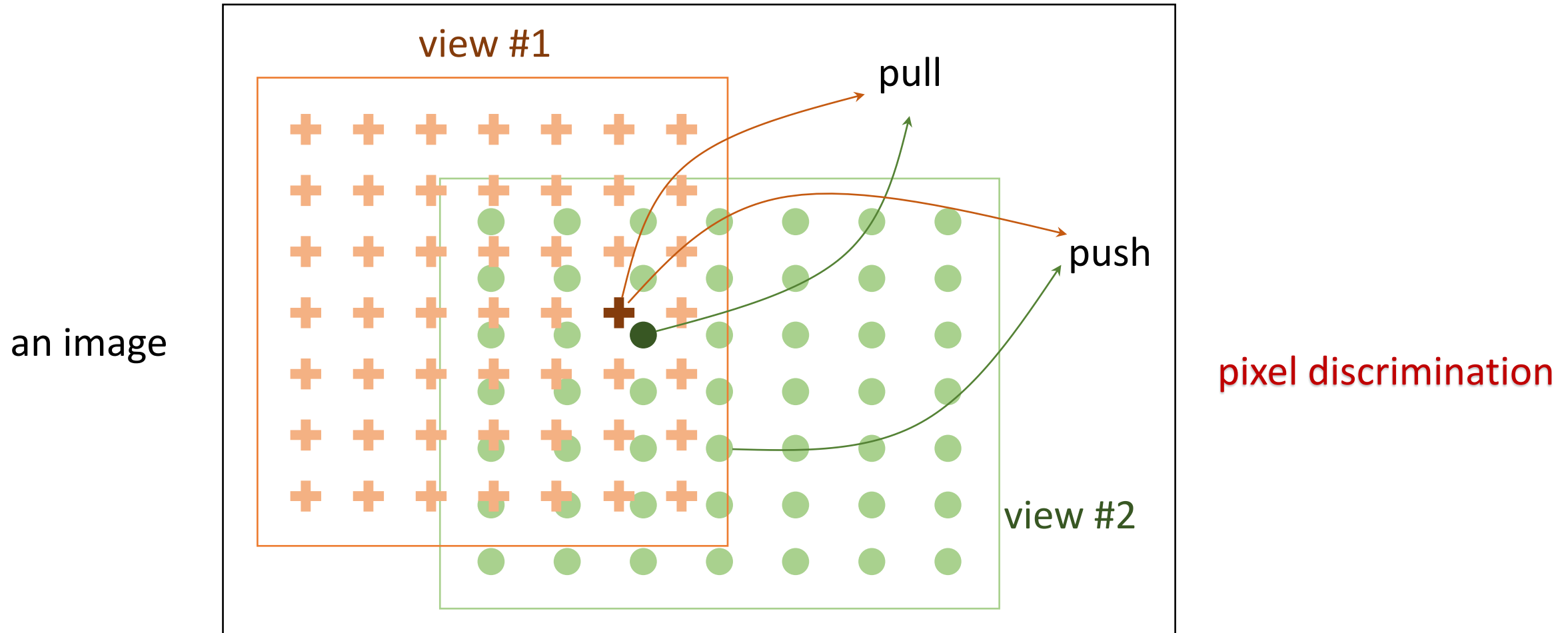


Previous pre-text tasks: **instance** discrimination

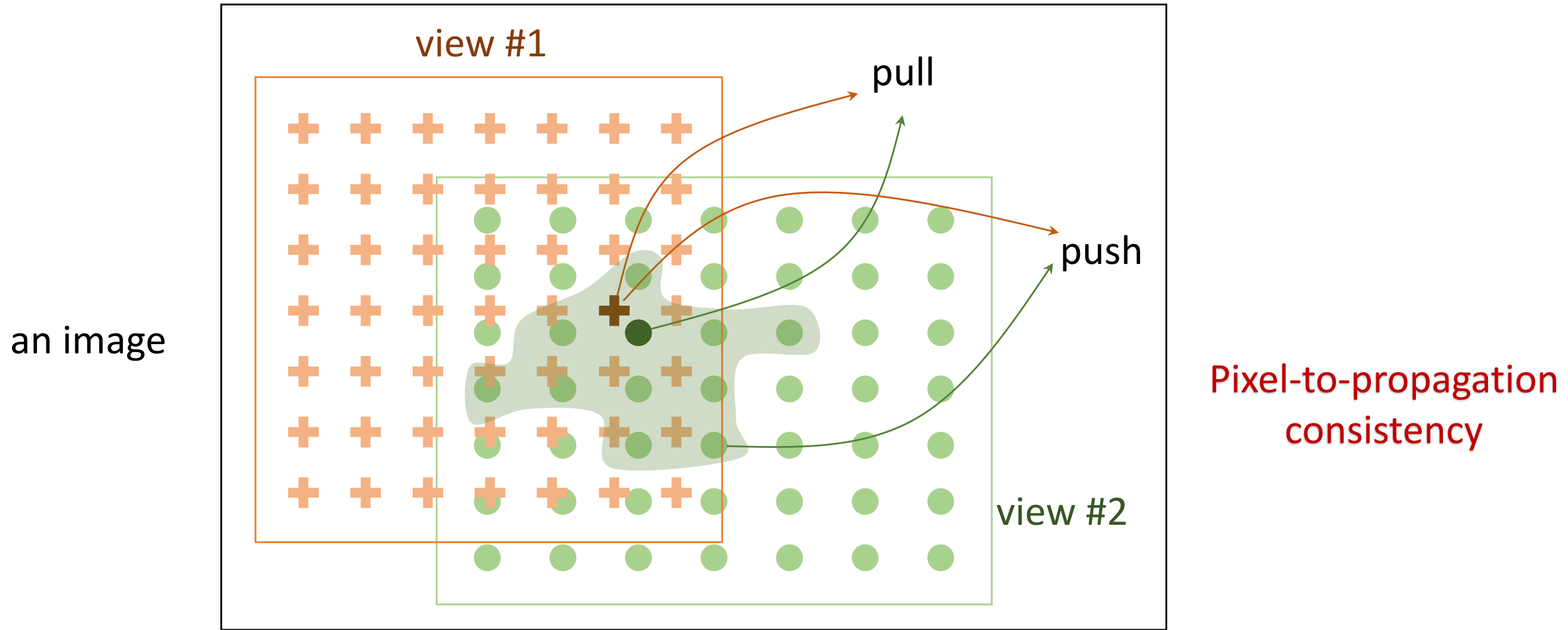


pixel-level pretext task

Pixel-Level Contrastive Learning



Pixel-to-Propagation Consistency



Pixel-to-Propagation Consistency

- Pixel contrast: spatial sensitivity
- Propagation: spatial smoothness

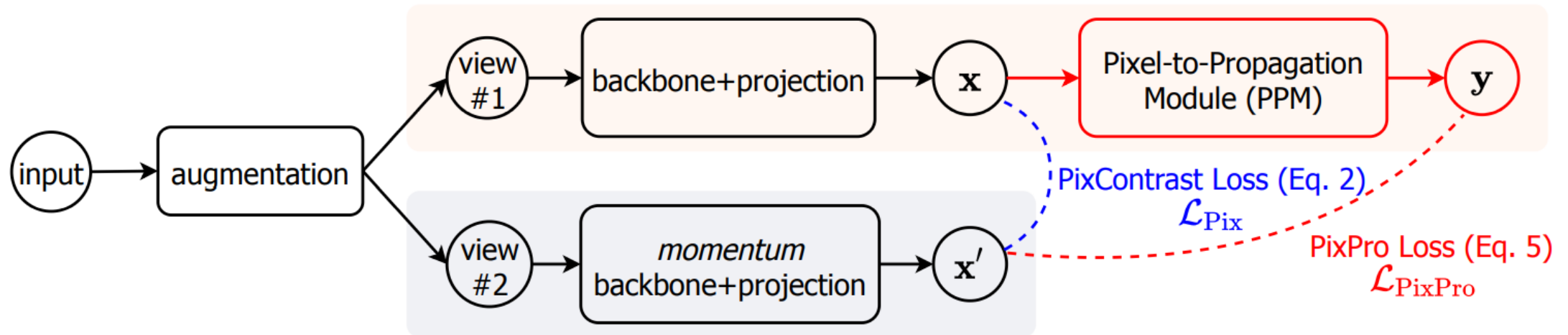
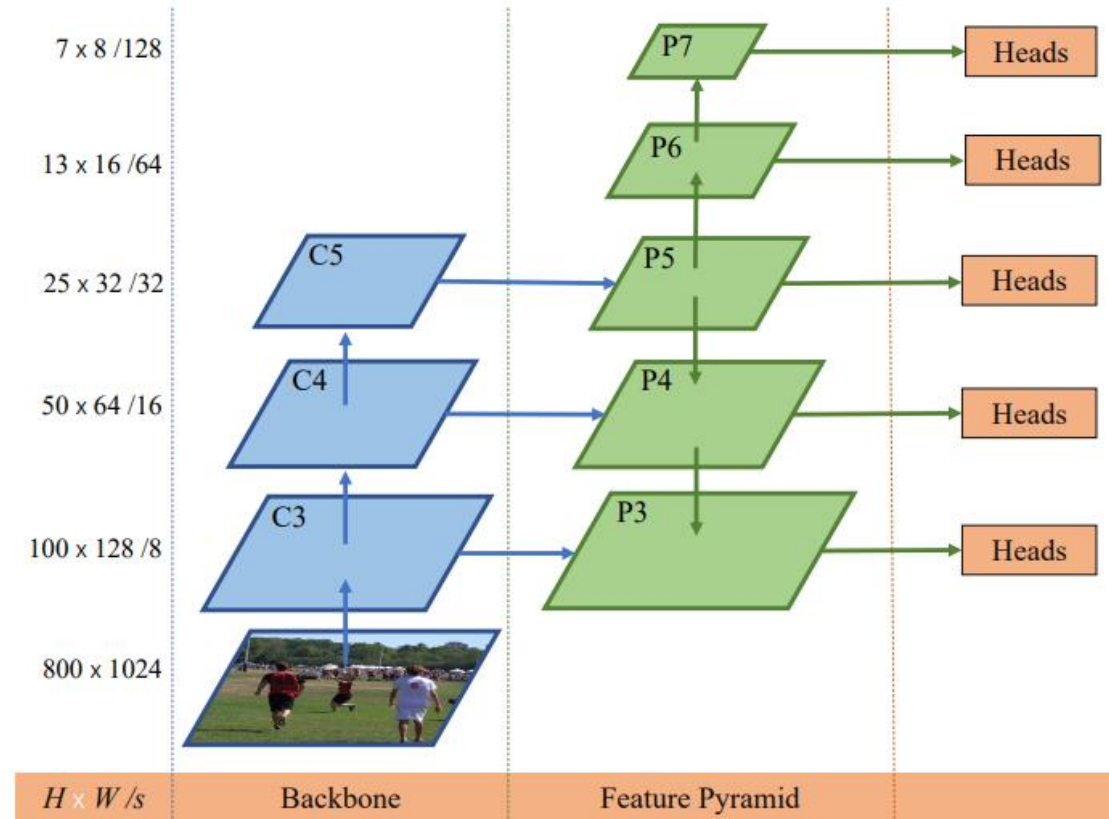


Figure 2. Architecture of the *PixContrast* and *PixPro* methods.

Aligning Pre-Training to Downstream Networks

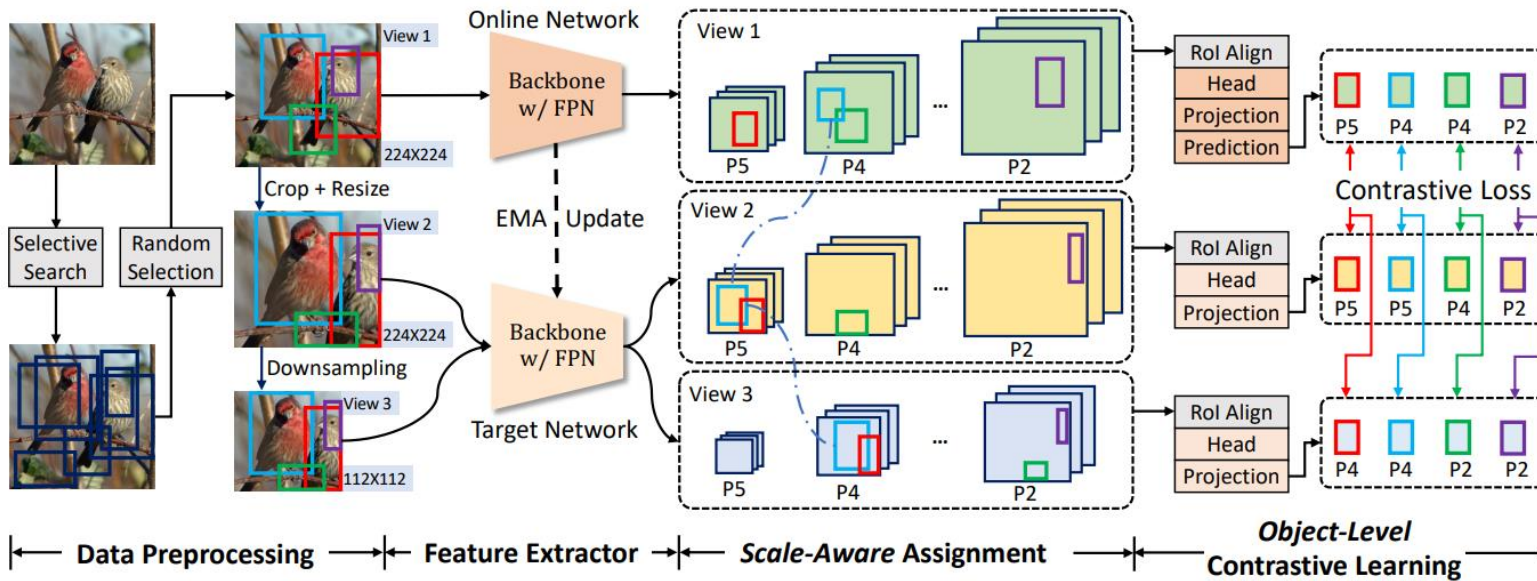
- Using the same architecture as in downstream tasks



An architecture in
FCOS detector

Object-Level Pre-Training

- Aligning pretraining for object detection
 - SoCo (NeurIPS'2021)



Object-Level Pre-Training (SoCo)

- Results

Table 1: Comparison with state-of-the-art methods on COCO by using Mask R-CNN with **R50-FPN**.

Methods	Epoch	$1\times$ Schedule						$2\times$ Schedule					
		AP ^{bb}	AP ₅₀ ^{bb}	AP ₇₅ ^{bb}	AP ^{mk}	AP ₅₀ ^{mk}	AP ₇₅ ^{mk}	AP ^{bb}	AP ₅₀ ^{bb}	AP ₇₅ ^{bb}	AP ^{mk}	AP ₅₀ ^{mk}	AP ₇₅ ^{mk}
Scratch	-	31.0	49.5	33.2	28.5	46.8	30.4	38.4	57.5	42.0	34.7	54.8	37.2
Supervised	90	38.9	59.6	42.7	35.4	56.5	38.1	41.3	61.3	45.0	37.3	58.3	40.3
MoCo [4]	200	38.5	58.9	42.0	35.1	55.9	37.7	40.8	61.6	44.7	36.9	58.4	39.7
MoCo v2 [5]	200	40.4	60.2	44.2	36.4	57.2	38.9	41.7	61.6	45.6	37.6	58.7	40.5
InfoMin [6]	200	40.6	60.6	44.6	36.7	57.7	39.4	42.5	62.7	46.8	38.4	59.7	41.4
BYOL [3]	300	40.4	61.6	44.1	37.2	58.8	39.8	42.3	62.6	46.2	38.3	59.6	41.1
SwAV [7]	400	-	-	-	-	-	-	42.3	62.8	46.3	38.2	60.0	41.0
ReSim-FPN ^T [41]	200	39.8	60.2	43.5	36.0	57.1	38.6	41.4	61.9	45.4	37.5	59.1	40.3
PixPro [10]	400	41.4	61.6	45.4	-	-	-	-	-	-	-	-	-
InsLoc [12]	400	42.0	62.3	45.8	37.6	59.0	40.5	43.3	63.6	47.3	38.8	60.9	41.7
DenseCL [11]	200	40.3	59.9	44.3	36.4	57.0	39.2	41.2	61.9	45.1	37.3	58.9	40.1
DetCon _S [13]	1000	41.8	-	-	37.4	-	-	42.9	-	-	38.1	-	-
DetCon _B [13]	1000	42.7	-	-	38.2	-	-	43.4	-	-	38.7	-	-
SoCo	100	42.3	62.5	46.5	37.6	59.1	40.5	43.2	63.3	47.3	38.8	60.6	41.9
SoCo	400	43.0	63.3	47.1	38.2	60.2	41.0	44.0	64.0	48.4	39.0	61.3	41.7
SoCo*	400	43.2	63.5	47.4	38.4	60.2	41.4	44.3	64.6	48.9	39.6	61.8	42.5

+1.8 mAP

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- More study on BYOL why it does not collapse
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- **Self-supervised learning on Transformers**
 - MoCo v3 (ICCV'2021), DINO (ICCV'2021)
 - SSL-Swin/MoBY/EsViT (tech report)

SSL on Transformers?

microsoft / [Swin-Transformer](#) Public

This is an official implementation for "Swin Transformer: Hierarchical Vision Transformer using Shifted Windows".

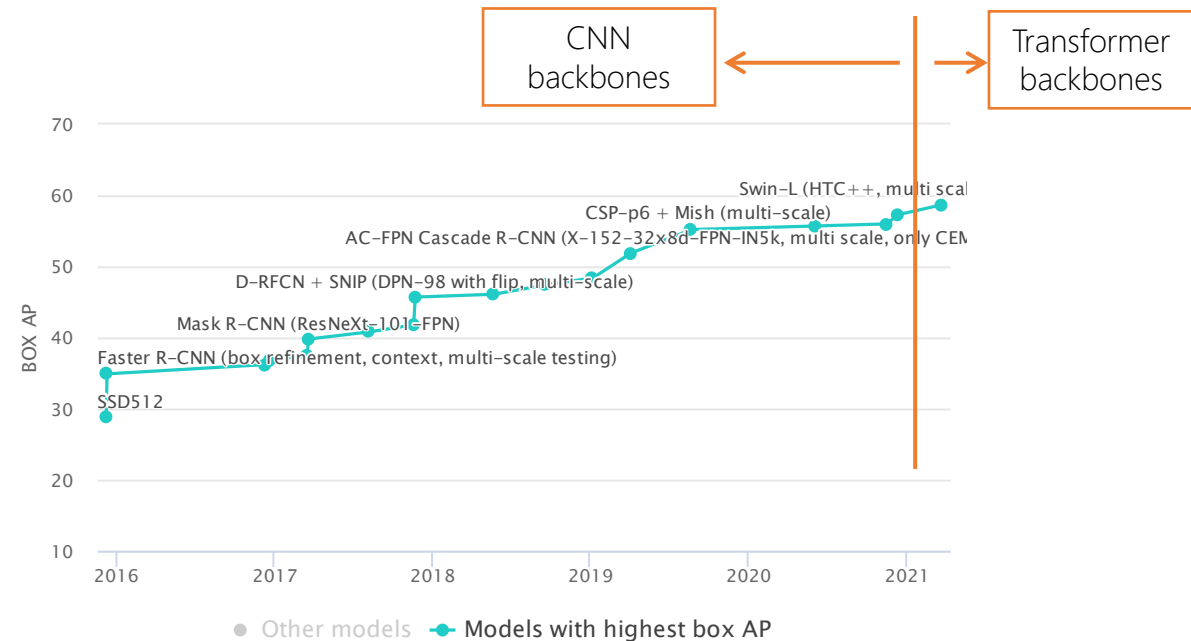
[arxiv.org/abs/2103.14030](#)

MIT License

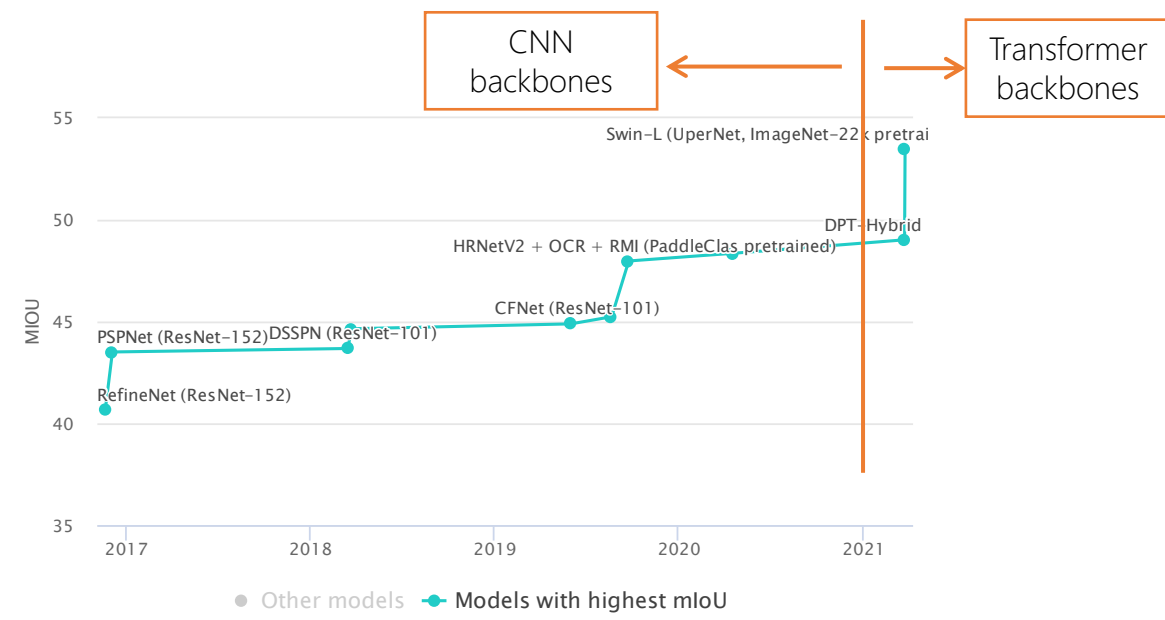
4.6k stars 592 forks

4600 stars

COCO object detection



ADE20K semantic segmentation

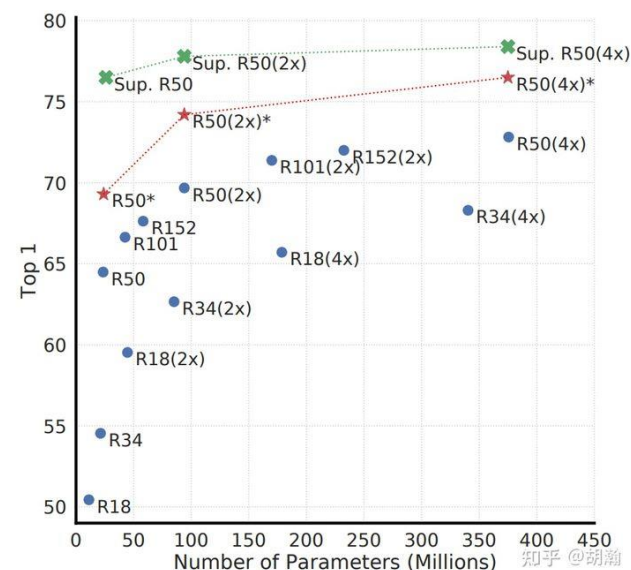



Evolving of state-of-the-art approaches for years

Self-Supervised Learning + Transformer

- “Golden combination”
 - SSL can better leverage the model capacity

- ▶ **“Pure” Reinforcement Learning (cherry)**
 - ▶ The machine predicts a scalar reward given once in a while.
 - ▶ **A few bits for some samples**
- ▶ **Supervised Learning (icing)**
 - ▶ The machine predicts a category or a few numbers for each input
 - ▶ Predicting human-supplied data
 - ▶ **10→10,000 bits per sample**
- ▶ **Self-Supervised Learning (cake génoise)**
 - ▶ The machine predicts any part of its input for any observed part.
 - ▶ Predicts future frames in videos
 - ▶ **Millions of bits per sample**



- Transformers have significantly stronger modeling power than CNN

<https://www.zhihu.com/question/457507120>

MoCo v3 (ICCV'2021)

- Transformer is difficult to be tamed for SSL
 - Fixed patch projection

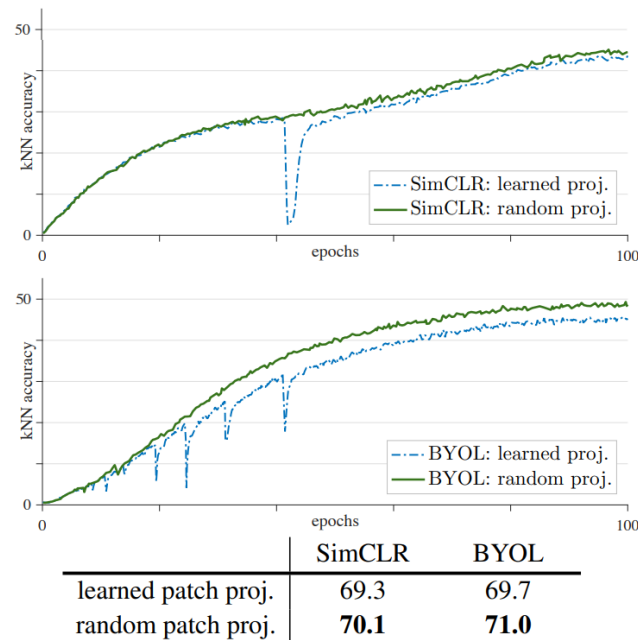


Figure 6. **Random vs. learned patch projection** (ViT-B/16, 100-epoch ImageNet, AdamW, batch 4096). **Top**: SimCLR: $lr=2e-4$, $wd=0.1$. **Bottom**: BYOL: $lr=1e-4$, $wd=0.03$.

DINO (ICCV'2021)

- Implicitly learns segmentation

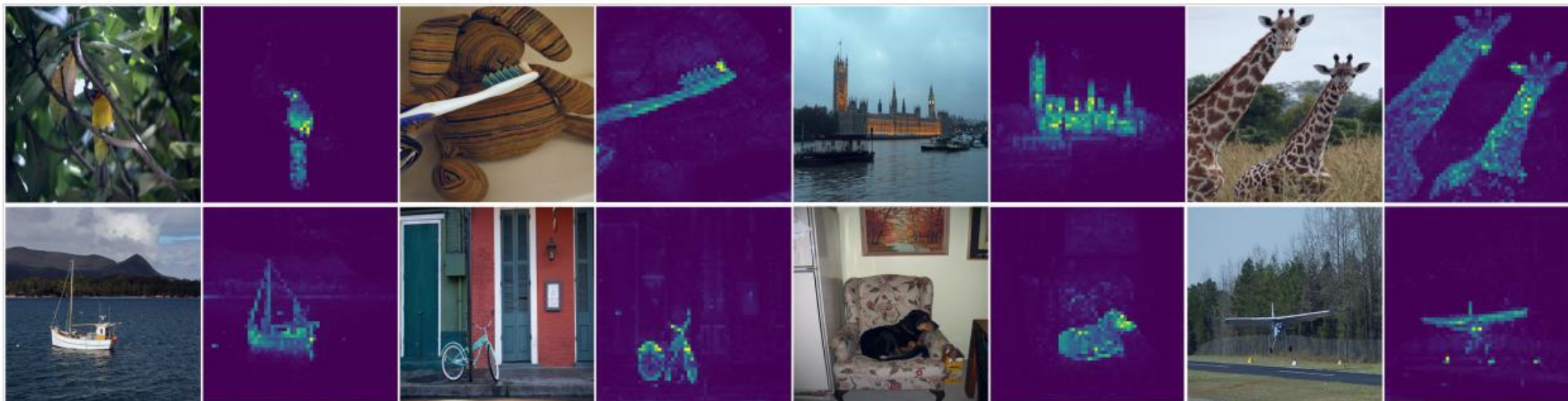
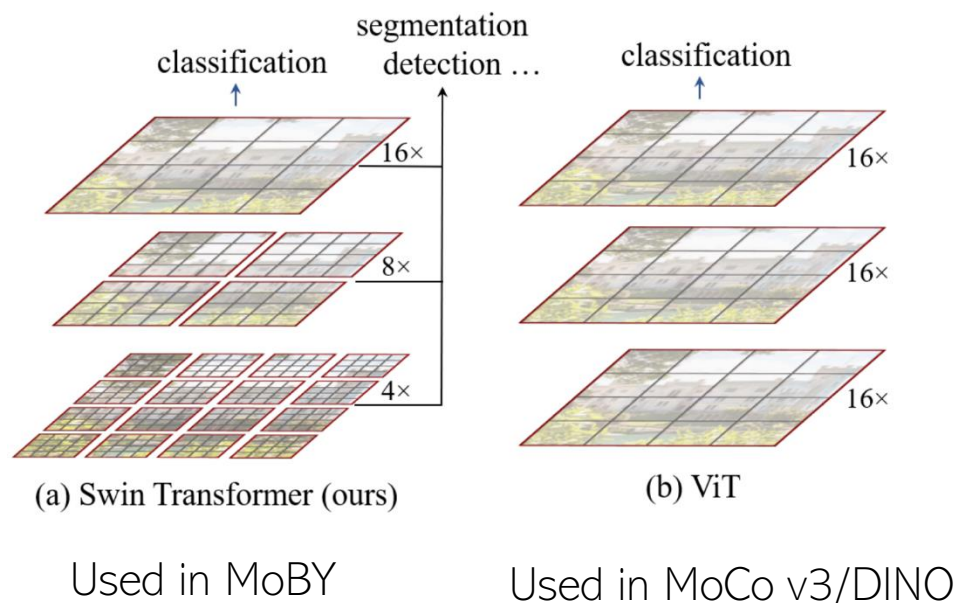


Figure 1: **Self-attention from a Vision Transformer with 8×8 patches trained with no supervision.** We look at the self-attention of the [CLS] token on the heads of the last layer. This token is not attached to any label nor supervision. These maps show that the model automatically learns class-specific features leading to unsupervised object segmentations.

SSL-Swin (MoBY)

- Provide baselines to evaluate transferring performance on down-stream tasks



- No better than supervised approaches

Method	Model	Schd.	box AP		
			mAP ^{bbox}	AP ₅₀ ^{bbox}	AP ₇₅ ^{bbox}
Swin-T (mask R-CNN)	Sup.	1x	43.7	66.6	47.7
	MoBY	1x	43.6	66.2	47.7
	Sup.	3x	46.0	68.1	50.3
	MoBY	3x	46.0	67.8	50.6
Swin-T (Cascade mask R-CNN)	Sup.	1x	48.1	67.1	52.2
	MoBY	1x	48.1	67.1	52.1
	Sup.	3x	50.4	69.2	54.7
	MoBY	3x	50.2	68.8	54.7

COCO object detection

Method	Model	Schd.	mIoU
Swin-T (UPerNet)	Sup.	160K	44.51
	MoBY	160K	44.06
	Sup. [†]	160K	45.81
	MoBY [†]	160K	45.58

ADE20K semantic segmentation

SSL-Swin (MoBY)

- Higher accuracy than DINO/MoCo v3, with much fewer additional tricks

Method	Arch.	Epochs	Params (M)	FLOPs (G)	img/s	Top-1 acc (%)	
Sup.	DeiT-S	300	22	4.6	940.4	79.8	
Sup.	Swin-T	300	29	4.5	755.2	81.3	
MoCo v3	DeiT-S	300	22	4.6	940.4	72.5	
DINO	DeiT-S	300	22	4.6	940.4	72.5	
DINO [†]	DeiT-S	300	22	4.6	940.4	75.9	+0.3 mAP vs. MoCo v3/DINO
MoBY	DeiT-S	300	22	4.6	940.4	72.8	
MoBY	Swin-T	100	29	4.5	755.2	70.9	+2.2 mAP vs. DeiT
MoBY	Swin-T	300	29	4.5	755.2	75.0	

Table 1: Comparison of different SSL methods and different Transformer architectures on ImageNet-1K linear evaluation. [†] denotes DINO with a multi-crop scheme in training.

<https://github.com/SwinTransformer/Transformer-SSL>

What's Next?

Open Crucial Questions

- Can SSL benefit from almost unlimited data?
- What is the relationship with multi-modality learning?
 - E.g., CLIP and DALL-E

Take-Home Message

- Enjoy the “cake”
- Two trends:
 - Aligning pre-training to downstream tasks
 - SSL + (Swin) Transformers
- Open critical questions
 - Can SSL benefit from almost unlimited data?
 - What is the relationship with multi-modality learning?

- ▶ **“Pure” Reinforcement Learning (cherry)**
 - ▶ The machine predicts a scalar reward given once in a while.
 - ▶ **A few bits for some samples**
- ▶ **Supervised Learning (icing)**
 - ▶ The machine predicts a category or a few numbers for each input
 - ▶ Predicting human-supplied data
 - ▶ **10→10,000 bits per sample**
- ▶ **Self-Supervised Learning (cake génoise)**
 - ▶ The machine predicts any part of its input for any observed part.
 - ▶ Predicts future frames in videos
 - ▶ **Millions of bits per sample**



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